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- [ZU 48] K. Zuse, "Über den Allgemeinen [sic] Plankalkül als Mittel zur Formulierung schematisch-kombinativer Aufgaben," Archiv der Mathematik 1 (1949), 441–449.
- [ZU 59] K. Zuse, "Über den Plankalkül," Elektronische Rechenanlagen 1 (1959), 68–71.
- [ZU 72] Konrad Zuse, "Kommentar zum Plankalkül," Berichte der Gesellschaft für Mathematik und Datenverarbeitung 63 (1972), Part 2, 36 pages. English translation, 106 (1976), 21–41.

Addendum

Two other languages, Transcode and PACT I, deserve to be part of the story as well, so they appear in Table 1 above although they were unfortunately missed by the authors when we first compiled this history.

Transcode was developed for the FERUT computer, a clone of the Ferranti Mark I that was installed at the University of Toronto in 1952. The authors of this language, J. N. P. Hume and B. H. Worsley, devised a way to cope with FERUT's awkward two-level storage that was more efficient than the AUTOCODE approach being taken independently by Brooker in Manchester, because they expected Transcode programmers to be aware of FERUT's overall characteristics. To perform the TPK algorithm they might have punched the following codes onto a paper tape:

```
000
       INST 019
                                      Inputs the following 19 Instructions.
      READ 001.0 000.0 X00.0
001
                                      Copies DRUM location 1 into X-page.
       ADDN CO1.0 CO1.0 ZO1.0
                                      Sets initial value of i = 10 - j to 5 + 5.
002
003
      BSET 000.5 000.0 000.0
                                      Sets initial value of B_5 to 0.
004
      LOOP 011.0 000.6 000.0
                                      Prepares to loop 11 times, using B_6.
                                      Places |a_i| - 0 in Z02.
005
      KOMP X11.5 CO2.0 ZO2.0
                                      Forms |a_i|^{1/2}.
       <sup>1</sup>/<sub>2</sub>QRT Z02.0 000.0 Z02.0
006
                                      Places a_i \cdot a_i in Z03.
007
      MULT X11.5 X11.5 Z03.0
008
      MULT X11.5 Z03.0 Z03.0
                                      Forms a_i \cdot a_i \cdot a_i.
      MULT C01.0 Z03.0 Z03.0
                                      Forms 5a_i \cdot a_i \cdot a_i.
009
010
       ADDN Z02.0 Z03.0 Z02.0
                                      Forms f(a_i).
```

```
SUBT C03.0 Z02.0 Z03.0
                                   Forms 400 - f(a_i).
011
      TRNS 014.0 000.0 Z03.0
                                   Transfers control if 400 - f(a_i) \ge 0.
012
                                   Enters 999 in place of f(a_i).
      OVER CO4.0 000.0 Z02.0
013
014
      PRNT 002.2 010.0 Z01.0
                                  Prints answers.
015
      SUBT Z01.0 C05.0 Z01.0
                                   Adjusts i to its next value.
                                   Adjusts B_5 to its next value.
016
      INCB 000.5 003.0 000.0
017
      TRNS 005.0 000.6 000.0
                                   Ends loop, adjusting B_6.
      HALT 000.0 000.0 000.0
                                   Programs a stop.
018
      QUIT 000.0 000.0 000.0
                                   Terminates the Instructions.
019
      CNST 5++ 1+100- 4+2+ 999+2+ 1++ " Specifies the five constants.
020
021
      NUMB a_0 a_1 \dots a_{10} "
                                  Specifies the input data.
022
      DRUM 001
                                  Stores block 1 of numerical data.
023
      ENTR
                                   Begins compilation and execution.
```

The variables in Transcode, other than those in B registers, were floating-point numbers X01, X02, ..., Y01, Y02, ..., Z01, Z02, ..., consisting of three 20-bit words each, namely a 40-bit signed fraction and a signed 20-bit exponent. But Transcode programmers didn't have to deal with binary notation; for example, the five constants C01 = 5, C02 = 0, C03 = 400, C04 = 999, C05 = 1 in the program above are specified on line $\theta 2\theta$ in decimal form as (mantissa) (sign) (exponent) (exponent sign). A constant like -.0073 would be '73-3-'; and the same conventions applied to input data in a NUMB specification such as line $\theta 21$. Notice that they used 1^{-100} for the constant zero(!). The PRNT command on line $\theta 14$ would output Z01 and Z02 to a line on FERUT's typewriter, showing both numbers in floating-point notation with ten significant digits.

Variables were stored backwards in memory, so that the address of the first word of XO2 was 3 locations less than the address of XO1. The main loop of this program, governed by instructions 003, 004, 016, and 017, is performed for eleven index register settings $(B_5, B_6) = (0, 30), (3, 27), \ldots, (30, 0)$; thus X11.5 is X11 the first time, then X10, ..., then X01. Meanwhile variable i = ZO1 steps through the values $10, 9, \ldots, 0$, because of instructions 002 and 015.

Programmers could say KOPY at the end, following ENTR; then the compiled instructions would be punched on paper tape, for subsequent use as a subroutine in other programs. Since paper tape code was equivalent to teletype code, programs could also be transmitted "online" to Toronto from remote sites in Canada. [For further details, see J. N. P. Hume and Beatrice H. Worsley, "Transcode: A system of automatic coding for FERUT," Journal of the Association for Computing Machinery 2 (1955), 243–252; J. N. Patterson Hume, "Development of systems software for the Ferut computer at the University of Toronto, 1952 to 1955," IEEE Annals of the History of Computing 16, 2 (Summer 1994), 13–19.]